

Traffic Relief

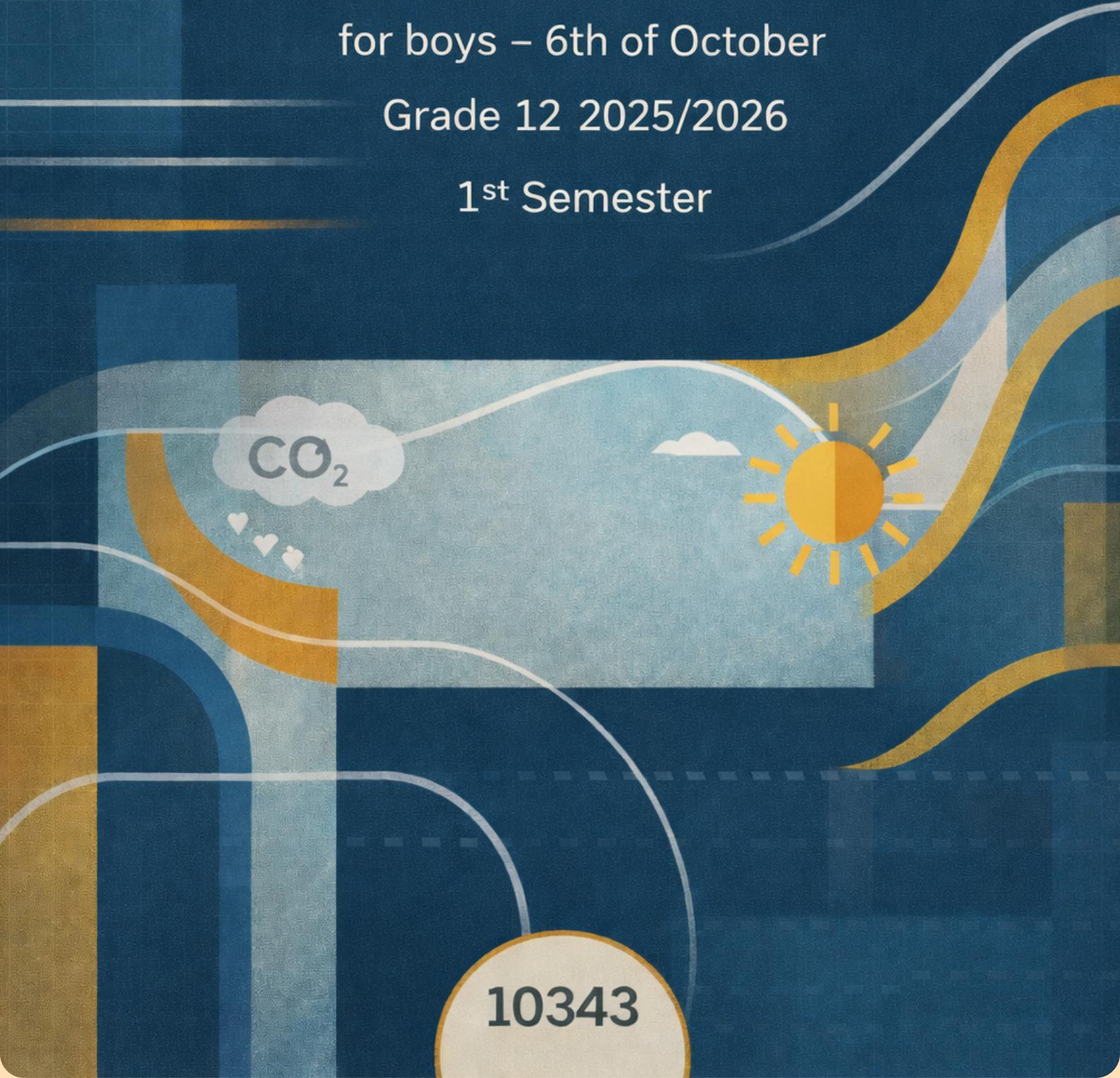
Moaz Mohamed

STEM High School

for boys – 6th of October

Grade 12 2025/2026

1st Semester



CO₂

10343

Weeks

Tasks

Proof

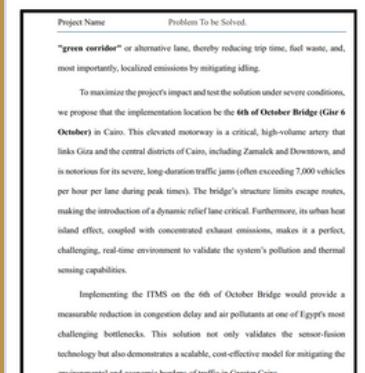
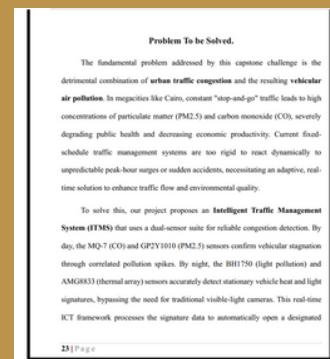
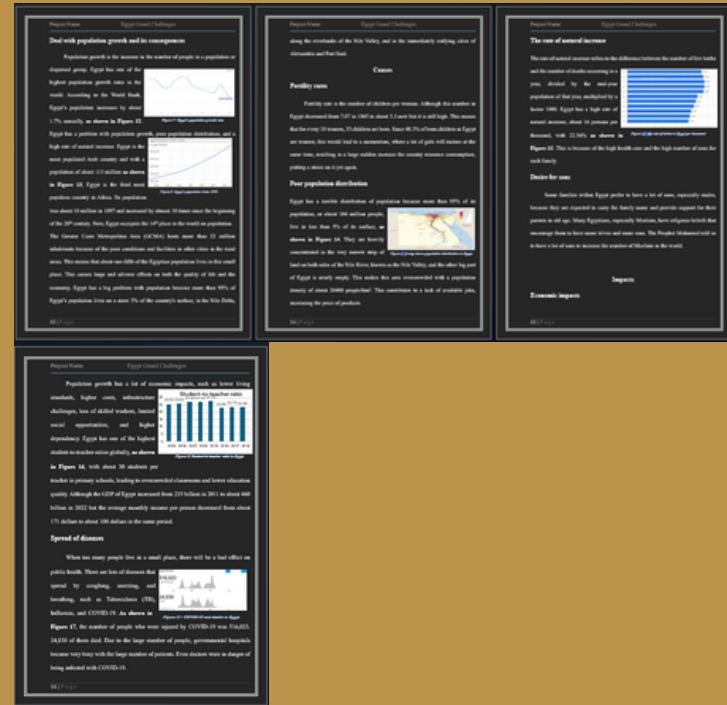
Week One

Week Two

Searching about the challenge and defining the specific problem to be solved and writing this section in the portfolio

Week Three

Working on the capstone project challenge and writing the grand challenges "Deal with population growth and its consequences"



Searching for prior
real-life solutions to
benefit from them
and writing about
“The CIRTA Traffic
Management
System”

Weeks

Week Four

Tasks

Reviewing the datasheet for sensors to ensure their suitability for the project

Proof

GP2Y1010AU0F Compact Optical Dust Sensor

AN-00010 Digital 16bit Serial Output Type Ambient Light Sensor IC

AN-00011 Ambient Light Sensor IC

AN-00012 Ramp Monitoring System

Week Five

Searching for previous solutions for the same challenge and the prior solution was written as shown

Ramp Monitoring (Specific Model: Los Angeles, California Freeway System)

Ramp Monitoring (Specific Model: Los Angeles, California Freeway System)

Ramp Monitoring (Specific Model: Los Angeles, California Freeway System)

Week Six

Buying materials (all sensors and the foam to simulate the road), and writing selection of prototype

Selection of Prototype

The prototype will be made of a 120 x 80 foam tile; the car lanes will be divided with a ratio of the real road. This foam is used as it is easier to work with compared to wood, while also being lighter than wood. The real cars will be replaced by small models, and the road lines will have the same ratio as the models. The sensors will be mounted on the side of this road connected to an Arduino, which will control the servo motor that will open the green line when the sensors detect a high amount of emissions. The sensors will also detect the change of the amount of emissions before and after the system is installed.

Weeks

Week Seven

Tasks

Writing the Methods and Test Plan sections in the poster and portfolio

Methods

1. The 3D design was done. **As shown in Figure 2.**
2. A large, flat piece of Styrofoam was used as the main base to provide a stable platform for mounting all components and simulating a roadway environment. **As shown in Figure 3.**
3. The styrofoam was covered with colored paper to simulate the road shape. **As shown in Figure 4.**
4. The sides of the road were mounted using wood sticks. **As shown in Figure 5.**
5. The MQ-7 gas sensor (CO) and the GP2Y1010 optical dust sensor (PM2.5) were placed near the roadway on a lighting pole on the roadside.
6. The Arduino controller was securely attached to the Styrofoam base using glue, tape, or small supports, serving as the central hub for the entire system.
7. The servomotor was connected to the Arduino controller and mounted on the Styrofoam base right next to the barrier arm's pivot point, representing the gate to the "green road."
8. All sensors, the servo motor, and power components were connected to the appropriate digital, analog, and power pins on the Arduino controller using jumper wires, following the circuit schematic for dual-mode operation. **As shown in Figure 6.**

Testplan

To demonstrate the project's applicability, the following tests were conducted. Each step of the test plan aims to test a specific design requirement.

1. A simulation was done to approximate the results on the 6th October Bridge.
2. Virtual sensors were put in the model to measure the flow rate and pollution levels before and after the opening of the secondary road.
3. The barrier mechanism was included in the simulation to show how the system redistributes the traffic. The timer was checked to ensure the barrier opens or closes within 3 seconds for safety.

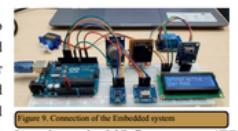


Week Eight

Writing an analysis point explaining the embedded system in our prototype

4. Embedded system

The embedded system, **shown in Figure 9**, centers around an Arduino controller, which monitors the complicated decision-making and management of the parts necessary for a trustworthy, 24-hour operation. The primary design of the system consists of time-based switching that proficiently controls two separate sensor systems, all **the controller** is mainly responsible for the sensor confirmation logic. It analyzes the MQ-7 gas sensor (CO) and the GP2Y1010 optical dust sensor (PM2.5) data during the day. Congestion will only be recognized if both sensors indicate high values at the same time. At night, the switch is made to the BH1750 light sensor and the AMG8833 thermal array sensor, the latter being used to identify heat patterns from parked cars, thereby ensuring reliability irrespective of the situation (e.g., in fog). Power management for pairs of sensors is an essential design specification for the Arduino; this means that only the designated sensors will be allowed to be on for their specific time. This plan directly complements the design objective of extending the life of each sensor effectively by two times. Once the Arduino has confirmed congestion, it will activate a servo motor or a relay to either raise a barrier or change a traffic signal to allow secondary road opening. The system will continue to function until the traffic situation is back to normal; then, the controller will instruct the actuator to close the secondary road.



Week Nine

Writing the “Abstract” section in the Poster

Abstract

For years, Egypt has grappled with numerous grand challenges that impede its development. This project specifically targets four of these challenges: Deal with urban congestion and its consequences, address and reduce pollution fouling our air, water, and soil, deal with population growth and its consequences, and work to eradicate public health issues and diseases. The purpose of the study is to address the problem of traffic congestion in urban areas, and the problem to be solved is to mitigate the chronic traffic jams on the 6th of October Bridge. The chosen solution was to construct a low-cost and reliable smart congestion detection and diversion system that can work both in day and night conditions. During the daytime, a CO detector and a dust-density detector are located at 2.5 meters high to assess the emissions that inevitably build up during slow or stopped vehicle movement. When night falls, and visual detection is unreliable, a temperature detector located 5 meters above ground level detects the heat generated by grouped vehicles as another congestion sign. The prototype underwent several tests to ensure that it successfully attained design requirements, as the average flow rate of vehicles has increased by more than 15% over a period of 5 minutes, and the amount of CO and PM2.5 was reduced to less than 10 PPM and 5 $\mu\text{g}/\text{m}^3$, respectively. Some negative results were shown at first but were overcome through adjustments. After gathering the results of the tests conducted, conclusions confirm the project's effectiveness for traffic control. Additionally, major findings prove that scaling the prototype could significantly contribute to solving Egypt's Grand Challenges and the specific problem of traffic management.

Weeks

Week Ten

Tasks

Writing the first Recommendation point about the real-life application

Week Eleven

Proof

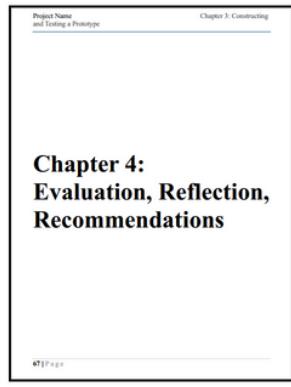
Writing Chapter four of the portfolio

Real-life application

The proposed project involves the development of a large-scale Intelligent Traffic Management System (ITMS) for the 6th of October Bridge in Cairo. **Shown in Figure 10**, it is a crucial 20.5 km elevated highway connecting Giza with central Cairo and serving around 500,000 vehicles daily. Despite its importance, the bridge experiences significant traffic congestion during peak hours, with vehicle volumes exceeding 7,000 per lane, leading to average speeds below 15 km/h and long riding times of over 45 minutes. The ITMS will monitor congestion along a 2 km test segment with four lanes in each direction, utilizing sensor clusters positioned 200 meters apart, night conditions. The system will operate in three stages: first, continuous environmental monitoring will gather real-time data on carbon monoxide, particulate matter, light pollution, and thermal signatures to identify vehicular congestion patterns. Second, intelligent decision-making will apply data-fusion algorithms to analyze gathered information and activate lane management protocols when congestion exceeds defined thresholds for more than 5 minutes. Lastly, during the control and actuation stage, high-precision servo motors and traffic signal controllers will be employed, managed by an Arduino-based central processing unit, to dynamically manage traffic flow by opening relief lanes or reversing lane directions based on real-time data and traffic density.



Figure 10. 6th of October Bridge



Traffic relief



TRAFFIC RELIEF

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Grade 12, (2025_2026)

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